

משוואות התנועה עבור זורם בלתי-דחיס

$\vec{u} = (u_r, u_\phi, u_z)$ - קואורדינטות גליליות (Cylindrical Polar coordinates)

משוואת הרציפות (Continuity eq.):

$$\frac{1}{r} \frac{\partial (ru_r)}{\partial r} + \frac{1}{r} \frac{\partial u_\phi}{\partial \phi} + \frac{\partial u_z}{\partial z}$$

משוואת Navier-Stokes:

$$\begin{aligned} \frac{\partial u_r}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_r - \frac{u_\phi^2}{r} &= -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left(\nabla^2 u_r - \frac{2}{r^2} \frac{\partial u_\phi}{\partial \phi} - \frac{u_r}{r^2} \right), \\ \frac{\partial u_\phi}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_\phi - \frac{u_r u_\phi}{r} &= -\frac{1}{\rho r} \frac{\partial p}{\partial \phi} + \nu \left(\nabla^2 u_\phi - \frac{2}{r^2} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r^2} \right), \\ \frac{\partial u_z}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_z &= -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \nabla^2 u_z, \end{aligned}$$

טנזור המאמץ (Stress Tensor):

$$\begin{aligned} \tau_{rr} &= -p + 2\mu \frac{\partial u_r}{\partial r} & \tau_{r\phi} &= \mu \left(\frac{1}{r} \frac{\partial u_r}{\partial \phi} + \frac{\partial u_\phi}{\partial r} - \frac{u_\phi}{r} \right) \\ \tau_{\phi\phi} &= -p + 2\mu \left(\frac{1}{r} \frac{\partial u_\phi}{\partial \phi} + \frac{u_r}{r} \right) & \tau_{\phi z} &= \mu \left(\frac{\partial u_\phi}{\partial z} + \frac{1}{r} \frac{\partial u_z}{\partial \phi} \right) \\ \tau_{zz} &= -p + 2\mu \frac{\partial u_z}{\partial z} & \tau_{zr} &= \mu \left(\frac{\partial u_z}{\partial r} + \frac{\partial u_r}{\partial z} \right) \end{aligned}$$

$u = (u_r, u_\theta, u_\phi)$ - (Spherical Polar coordinates) קואורדינטות כדוריות

משוואת הרציפות (Continuity eq.):

$$\frac{1}{r^2} \frac{\partial(r^2 u_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(u_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial(u_\phi)}{\partial \phi}$$

משוואת Navier-Stokes:

$$\begin{aligned} & \frac{\partial u_r}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_r - \frac{u_\theta^2 - u_\phi^2}{r} \\ &= -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left(\nabla^2 u_r - \frac{2}{r^2 \sin^2 \theta} \frac{\partial(u_\theta \sin \theta)}{\partial \theta} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} - \frac{2u_r}{r^2} \right), \\ & \frac{\partial u_\theta}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_\theta + \frac{u_r u_\theta}{r} - \frac{u_\phi^2 \cot \theta}{r} \\ &= -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + \nu \left(\nabla^2 u_\theta - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} \right), \\ & \frac{\partial u_\phi}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_\phi + \frac{u_r u_\phi}{r} + \frac{u_\theta u_\phi \cot \theta}{r} \\ &= -\frac{1}{\rho r \sin \theta} \frac{\partial p}{\partial \phi} + \nu \left(\nabla^2 u_\phi + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi}{r^2 \sin^2 \theta} \right), \end{aligned}$$

טנזור המאמץ (Stress Tensor):

$$\begin{aligned} \tau_{rr} &= -p + 2\mu \frac{\partial u_r}{\partial r} & \tau_{r\theta} &= \mu \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} + \frac{\partial u_\theta}{\partial r} - \frac{u_\theta}{r} \right) \\ \tau_{\phi\phi} &= -p + 2\mu \left(\frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_r}{r} + \frac{u_\theta \cot \theta}{r} \right) & \tau_{\theta\phi} &= \mu \left(\frac{1}{r \sin \theta} \frac{\partial u_\theta}{\partial \phi} + \frac{1}{r} \frac{\partial u_\phi}{\partial \theta} - \frac{u_\phi \cot \theta}{r} \right) \\ \tau_{\theta\theta} &= -p + 2\mu \left(\frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} \right) & \tau_{\phi r} &= \mu \left(\frac{\partial u_\phi}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial u_r}{\partial \phi} - \frac{u_\phi}{r} \right) \end{aligned}$$